

# PERFORMANCE ANALYSIS OF HIGH EFFICIENCY LOW DENSITY PARITY-CHECK CODE DECODER FOR LOW POWER APPLICATIONS

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## ABSTRACT

In this study, we propose a low power, high efficient Low Density Parity-Check Code (LDPC) Decoder Architecture for error detection and correction applications. LDPC codes have been adopted in latest wireless standards such as satellite and mobile communications since they possess superior error-detecting and correcting capabilities. As technology scales, memory devices become larger and more powerful and low power consumption based error correction codes are needed. This study discusses the design and analysis of check node unit and variable node unit in LDPC decoder. The architecture is synthesized on Xilinx 9.2i and simulated using Modelsim, which is targeted to 90 nm device. Synthesis report shows that the proposed architecture reduces the hardware utilization and power consumption when compared to the conventional architecture design.

**Keywords:** LDPC Decoder, Node Architecture, Variable Node, Check Node

## 1. INTRODUCTION

Low Density Parity-Check (LDPC) codes are known to have excellent performance for high speed data transmission and low complexity. However, moderate-length or short length binary LDPC codes have been shown to have an early error floor and degraded decoding performance. These codes have been implemented in various standards such as WiMax (IEEE 802.16) and other high speed applications, where parallel implementations of iterative message-passing algorithms are ideally used in LDPC decoding. Reducing the complexity of the algorithm means to reduce the chip size and power consumption, at the same time increasing the throughput. Hence, Min-Sum (MS) algorithm was used to solve this issue. LDPC codes are suitable for iterative decoding, i.e., an iterative decoder can perform consecutive decoding of both rows and columns. LDPC implements parallelism in the decoding process thereby achieving high decoding throughput.

There are several decoding algorithms conventionally used. Out of these, the Belief Propagation (BP) algorithm attains an excellent decoding performance. For the standard BP algorithm, numerous multiplicative and logarithmic computations are necessary to compute the check node. The Min-Sum (MS) algorithm, interchanges the product term with the minimum value. Even though performance is reduced, the hardware complexity of the BP algorithm is significantly minimized, by replacing complex computations of check nodes with simple summation and comparison operations. The min-sum algorithm provides a less sensitivity in decoding performance under finite word-length implementations and do not require channel information. Due to this advantage, MS algorithm is widely used.

The study presents a novel design for LDPC decoder operating at low power and designed over a smaller silicon area. The remaining sections are organized as follows: In section 2, the literature review is presented. In section 3, the design of variable and check nodes

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architectures has been discussed. In section 4, the simulation results are given and analyzed. Section 5 summarizes the method giving the conclusions.

## 2. RELATED WORKS

Boutillon *et al.* (2013) proposed the serial GF(64)-LDPC decoder based on the Extended Min-Sum algorithm. Their decoder design obtained a performance at less than 0.7dB from the Belief Propagation algorithm for different code rates and lengths. Their design easily adapts in decoding very high Galois Field orders, such as GF(4096) or higher. The experimental results showed that the decoder area is less than 20% of a Virtex 4 FPGA for a decoding throughput of 2.95 Mbps.

The method proposed by Reviriego *et al.* (2013) relies on majority logic decoding serially with simple hardware. The method detects whether a word has errors in the first iteration of majority logic decoding and when it is error-free, the decoding ends before completion of the remaining iterations. Since most words in a memory are without errors, the average decoding time is greatly reduced. The method has been applied to a similar technique called Euclidean Geometry Low Density Parity Check (EG-LDPC) codes which is one step majority logic decodable. The experimental result shows that the method estimates the probability of error detection for different code sizes and numbers of errors accurately and is effective for EG-LDPC codes.

Sangmin and Sobelman (2013) finite precision effects in non-binary mixed-domain LDPC decoders were analyzed. It is shown how improved decoding performance can be achieved by using an offset-based method and proper scaling techniques. In addition, a novel Fast Fourier Transform (FFT)-based Belief Propagation (BP) decoder architecture was proposed balancing the computational load between processing units. The results showed that the method requires 47% reduced number of field programmable gate array slices compared to a standard FFT-based BP architecture.

Seong-In and Lee (2013) investigated the various methods for constructing Block-Circulant (BC) Reed-Solomon-Based Low-Density Parity-Check (RS-LDPC) codes. The proposed technique results in a BC form of a parity-check matrix from a random parity-check matrix for RS-LDPC codes. A decoder architecture and switch network for BC-RS-LDPC code was developed based on the new BC parity-check matrix. BC-RS-LDPC decoder architecture is designed with high performance to demonstrate the efficiency of the technique. The results show that the designed decoder required 1.3 M gates at

an operating frequency of 450 MHz to achieve a data throughput of 41 Gbps with 8 iterations.

Swapna and Anbuselvi (2012) designed a LDPC decoder using wave pipelining concept, which reduces the level of latency of the decoding process. This study provided the detailed internal architecture and its design complexity in terms of hardware utilization factors.

Yao *et al.* (2011) presented the design of memory efficient LDPC decoder by reducing the quantization word length of decoding information thereby minimizing the hardware complexity. Two quantization schemes were proposed to reduce the number of memory bits required by decoder design by using short word length with guaranteed Bit-Error-Rate (BER). Their results showed that the two quantization schemes simplifies the hardware complexity with very little loss of decoding performance.

## 3. PROPOSED DECODER ARCHITECTURE

The decoder designed using our method consists of two processing elements-Check Node Unit (CNU) and Variable Node Unit (VNU) as shown in Fig. 1. The CNUs and VNUs are connected through the routing network. Input and output edges of the check node unit are labeled by the connectivity given by parity-check matrix. The final outputs are taken from the VNU after the required numbers of iterations have been completed.

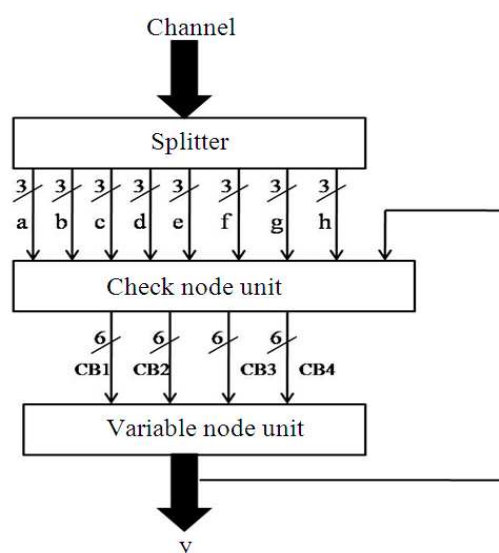


Fig. 1. LDPC decoder design overview

### 3.1. Check Node Architecture

The architecture of the proposed check node module of LDPC decoder is shown in Fig. 2. It is used in determining the strength of the received signal against noises in the channel. Four directional difference vectors are calculated with twelve |SUB|, four ADD and four sorter and concatenator modules. Then, the value of smallest difference is decided by using the sorter and concatenator units shown in Fig. 3. In the proposed design, ADD and subtractor units are required for the design of check node.

Since, the gate count or hardware complexity of one multiplier or division is much more than one adder or subtractor unit, all multipliers or divisions are replaced by adder or subtractor unit, thereby reducing the hardware cost.

After addition and subtractions are determined on received sequences, the sorting and concatenation is

performed on these sequences in order to compute the response of the check node unit in LDPC decoder. Each check node block produces 6 bit length of sequence and thus it produces 24 bit length sequence.

### 3.2. Variable Node Architecture

The variable node unit architecture shown in Fig. 4 computes the hard decision vector  $x$ . This vector is routed through the routing network to the Check Node Block (CNB). The routing between two nodes has single-bit value and the routing network size is smaller compared to that used in sum product algorithm. The variable node processor unit is comprised of a flip-detection circuit, line buffer, multiplexed adder and concatenator. Initially the received signal  $y$  from check node unit, is fed to the Variable Node Block (VNB) through a register-feedback assembly.

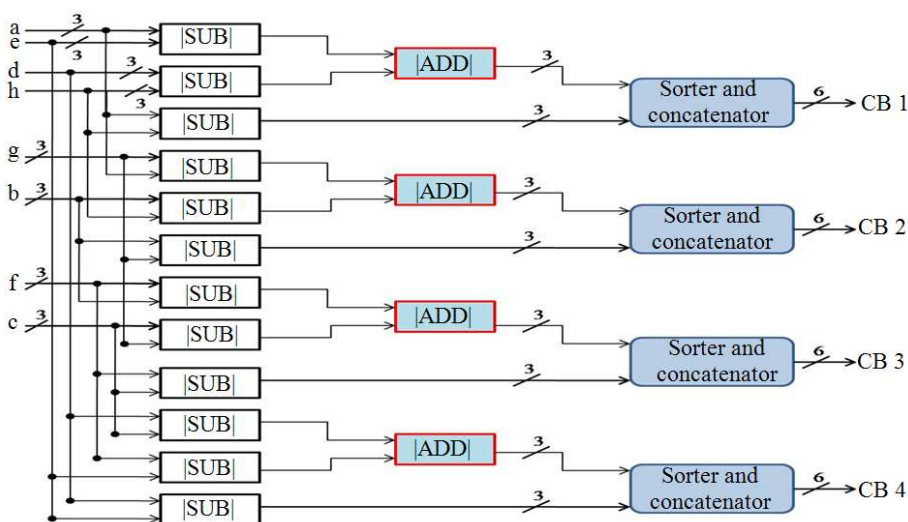


Fig. 2. Check node architecture design

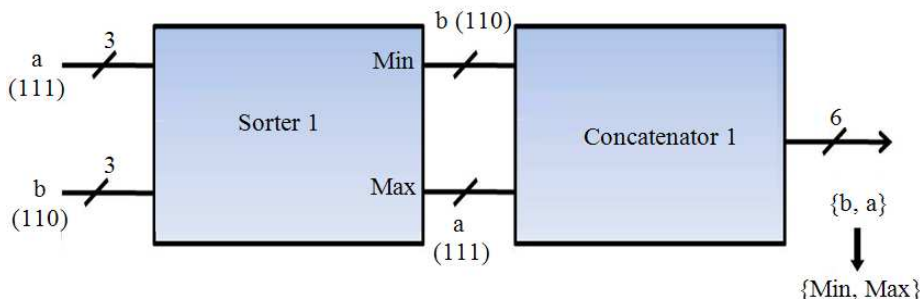


Fig. 3. Internal block of sorter and concatenator

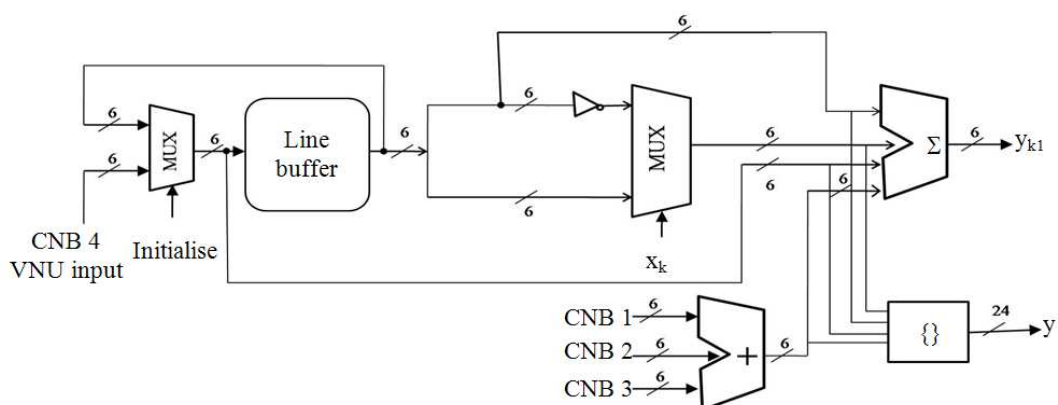


Fig. 4. Variable node architecture

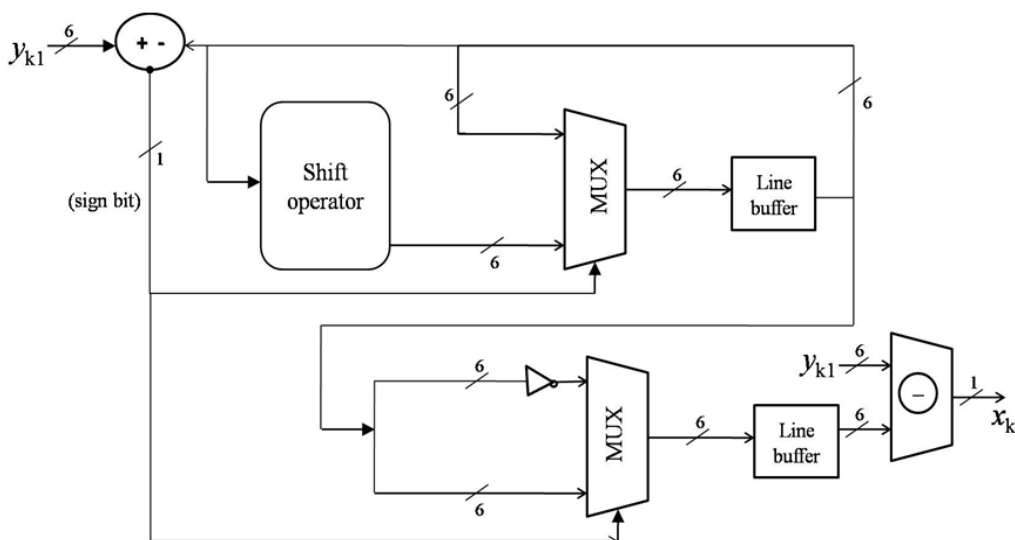


Fig. 5. Generation of control signal x<sub>k</sub>

The received values are 6-bit Signed-Magnitude (SM) values. Let [sn: mn] be n<sup>th</sup> 4-bit value provided to the n<sup>th</sup> VNB, where sn denotes hard decision value and mn denotes the magnitude of the same. The SM makes the correlation calculation simple to be implemented. The correlator circuit consists of an inverter followed by a 1-bit multiplexer. The proposed VNA unit consists basic multiplexer, line buffer, summer and concatenator modules. The block datas received from CNU unit are divided in to four sub blocks. The first three sub module blocks are processed by adder module and last sub module block

is processed directly by multiplexer unit. The control signal for multiplexer module acts as a select line in this unit, which is generated and illustrated in Fig. 5.

Figure 5 explains the generation of control signal (x<sub>k</sub>). The signed bit input is applied to the shift operator. The multiplexers and line buffers help in producing the control signal, which is fed to the VNU. The use of simple computational methodologies along with less row and column weights reduces the operations thereby, resulting in significantly less power consumption.

The subtraction unit receives six bits from variable node architecture and line buffer unit and thus produces

single sign bit which satisfies the following constraint Equation (1 and 2):

$$x_k = 1 \text{ if } (y_{k1} - \text{output of line buffer}) \geq 0 \tag{1}$$

$$x_k = 0 \text{ if } (y_{k1} - \text{output of line buffer}) < 0 \tag{2}$$

#### 4. RESULTS

The proposed LDPC coded based CDMA architecture system is tested on a Spartan-3E family device XC3S500E using Modelsim 5.8 and Xilinx 9.2i. This proposed scheme utilized 100 LUTs and 56 slices at a maximum frequency of 200 MHz. The proposed work results shows that the system incorporated with LDPC leads to lower power consumption in terms of slices, Look Up Tables and Flip Flops. The various devices in the Spartan-3 family are tested against their power and quiescent voltages and tabulated in **Table 1 and 2**, respectively.

The power utilization details of Spartan family are illustrated graphically in **Fig. 6**.

The parameters considered for investigation include number of Slices (S), number of Look Up Table (LUT's), Slice Latches (SL), gate counts (GA), Power Consumption (PC) and Area Utilization. All these parameters are tabulated in **Table 3** and graphically plotted in **Fig. 7**, respectively.

The performance based on decoding latency and LUTs has also been assessed and tabulated in **Table 4**. The other performance evaluation parameters used for our analysis are listed below.

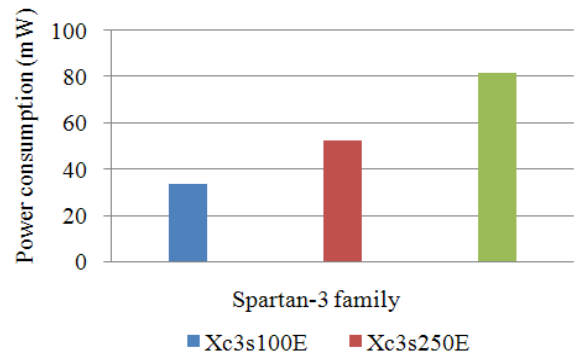
The Area Utilization (AU) is defined as follows Equation (3):

$$AU = \frac{\text{Area of active modules}}{\text{Area of total modules}} \times 100\% \tag{3}$$

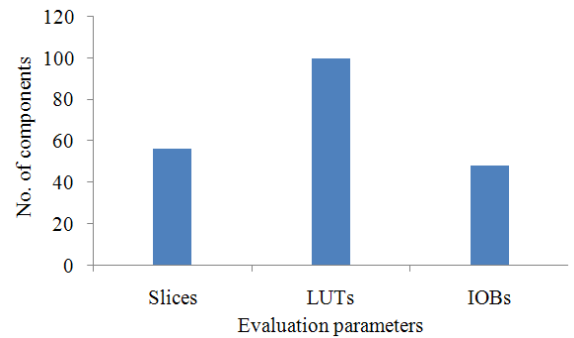
In this study, the area utilization is 1.2. The value of AU does not validate which design is superior to the others, but it just provides an evaluative method for reference.

#### 5. DISCUSSION

The proposed LDPC design has been evaluated in various Spartan 3E devices for comparing the power utilizations. The main objective of proposed decoder is to operate at a reduced power level. The comparison of power utilizations of various Spartan devices have been discussed in **Table 1**.



**Fig. 6.** Graphical illustration of power utilization



**Fig. 7.** Graphical plot for hardware utilization

**Table 1.** Comparison of power consumptions of Spartan-3 family

FPGA family	Device specifications	Power consumption
Spartan-3E	Xc3s100E	33.59 mW
Spartan-3E	Xc3s250E	52.29 mW
Spartan-3E	Xc3s500E	81.37 mW

**Table 2.** Comparison of quiescent voltages for spartan-3 family

FPGA family		Xc3s500E	Xc3s250E	Xc3s100E
Quiescent $V_{ccint}$	1.20V	26 mA	15 mA	8 mA
Quiescent $V_{ccaux}$	2.50V	18 mA	12 mA	8 mA
Quiescent $V_{cco25}$	2.50V	2 mA	2 mA	2 mA

**Table 3.** Performance analysis of hardware utilization

Performance parameters	Proposed architecture
Slices	56
LUTs	100
Gate Counts	2304
IOBs	48

**Table 4.** Performance comparison

Methodology	Decoding latency (ns)	LUTs
Proposed	28.00	100
Sangmin and Sobelman (2013)	56.36	6422
Spagnol <i>et al.</i> (2009)	50.05	12924

A number of performance evaluation and resource utilization parameters are determined for the proposed LDPC decoder. The present research is focused on the design and development of pipelined LDPC decoder for low power applications.

The proposed LDPC decoding architecture is synthesized using Xilinx project navigator version 9.2i tool. The proposed architecture provided decoding latency of 28 ns for both check node and variable node implementation. Sangmin and Sobelman (2013) achieved the decoding latency about 56.36 ns while Spagnol *et al.* (2009) achieved decoding latency about 50.05 ns. The proposed LDPC architecture is performed as superior in this way. Also, the proposed architecture consumed 4-input LUTs about 100. Sangmin and Sobelman (2013) consumed 6422 LUTs and Spagnol *et al.* (2009) consumed 12924 LUTs with respect to their various designing methodologies. The comparison is illustrated in **Table 4**.

## 6. CONCLUSION

For the LDPC codes used in low power wireless networks and wireless sensor devices, power consumption and hardware utilization are essential. This study obtained results and analyses the low power LDPC decoding architecture incorporating check node and variable node. This proposed LDPC architecture are designed and tested on various FPGA hardware platform, its hardware utilization and power consumption are discussed with its proposed architecture. This proposed LDPC decoder is well suitable for low power mobile applications which consumes minimum of 81.37 mW of energy. Even though it provides low power consumption, the hardware complexity and area utilization is high. This is the limitation of this research. To overcome such limitation, hybrid node architecture which combines the features of check node and variable node, may be used in future.

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